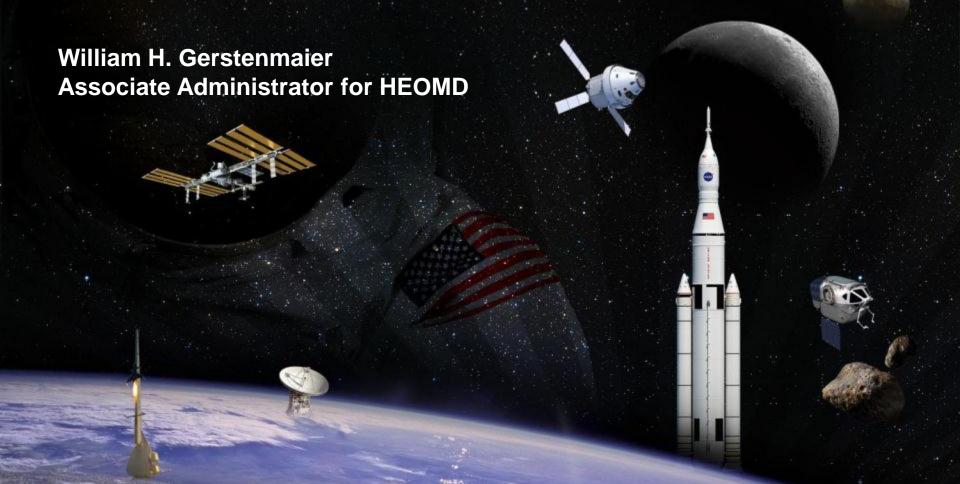


# **HEOMD NASA Advisory Council Public Session**



## What Were HEO's Biggest Accomplishments In 2013?



- Safe and successful operation of the ISS;
- ISS utilization: increase crew hours, benefits to humanity, new capabilities like rodent research on SpaceX 4
- Successful accomplishment of the Commercial Cargo Program, resulting in two providers of ISS cargo transportation services
- Received and evaluated the initial Certification Products Contracts
   Phase I products
- Successful accomplishment of the CCiCAP partners' milestones
- SLS preliminary design review
- Installation of SLS manufacturing tooling at Michoud Assembly Facility
- Delivery of Orion heatshield
- Orion power on
- Successful launches of TDRS-L, Landsat 8, and MaVEN
- Successful Lunar Laser Comm Demonstration from LADEE spacecraft in lunar orbit
- Initial definition of the Asteroid Redirect Mission

## What Are HEO's Biggest Challenges In 2014?



- Extending ISS beyond 2020 enables the nation's goals in space commercialization, extending humans beyond low Earth orbit, returning benefits & humanity, and leading a global exploration partnership
- Continue safe, innovative and productive use of ISS, including achieving a regular cadence of commercial cargo flights. Most important thing is to use this unique facility to expose others to the benefits of space based research
- Receive, evaluate, and select CCtCAP provider(s)
- Deliver the Orion test article and fly EFT-1
- Guide SLS through Agency approval for final design and fabrication, and continue hardware development as the overall design matures to critical design review
- Establish the pathway for SLS upper stage development including international partner roles
- Keep Orion and the ESA service module on track
- Take ARM Mission into formulation
- Launch TDRS-L successfully and implement Space Network Ground Segment Sustainment



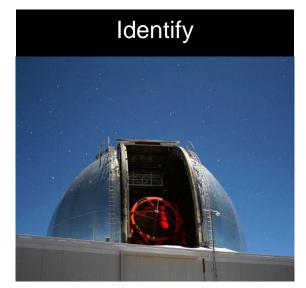
## Leveraging Capabilities for an Asteroid Mission



- NASA is leveraging key on-going activities in Science, Space Technology, and Human Exploration and Operations Mission Directorates
  - Asteroid identification and characterization efforts
  - High power solar electric propulsion
  - Autonomous guidance and control
  - Orion and Space Launch System vehicles
  - Technologies for astronaut extra-vehicular activities
- Each individual activity provides an important capability in its own right for human and robotic exploration
- We are working to utilize all of these activities to
  - Identify and redirect a small asteroid to a stable orbit in the lunar vicinity; and
  - Investigate and return samples with our astronauts.
- The FY14 budget supports continued advancement of the important individual elements and furthers the definition of the overall potential mission.

### **Asteroid Redirect Mission**





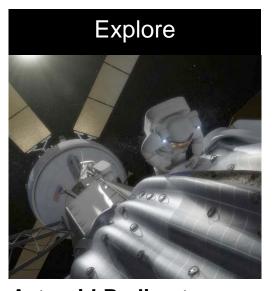
Asteroid Identification:

Ground and space based near Earth asteroid (NEA) target detection, characterization and selection



**Asteroid Redirect Robotic Mission:** 

High power solar electric propulsion (SEP) based robotic asteroid redirect to lunar distant retrograde orbit



Asteroid Redirect Crewed Mission:

Orion and Space
Launch System
based crewed
rendezvous and
sampling mission to
the relocated asteroid

## **Alignment Strategy for a Mission**

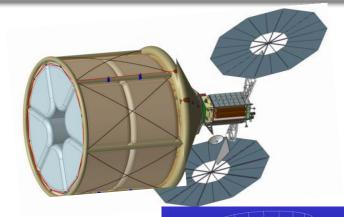


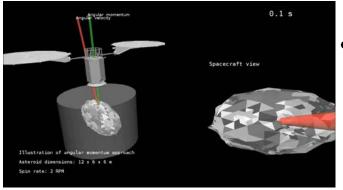
	2013	2014	2015	2016	2017	2018	2019	2020	2021	2022	2023
Asteroid Identify Segment	SST	PS-2	NEO I	Potential GEO- hosted payload detection	 						
		Enhanced assets candidates for developm	further		Final target selection						
Asteroid Redirect Robotic Mission								(i)			
		THIS SEC	SMENT TII NAL- BASE	MELINE							
			NAL- BASE ENCE MIS			Mission		Astonois			
		ner en				launch & SEF demo		Asteroid rendezyન્યુ & દ્રિક્ષ્યુપ્રધા	us	ma to	teroid neuver lunar icinity
Asteroid									No.		
Redirect Crewed Mission											
		First flight of Orion			EM-1: Un-cre Orion tes beyond	t		(t	M-2: Crew o beyond the o asteroid de on timeline o	Moon pending f asteroid	
					the Moor	n			redirec	<b>t)</b>	7

## **Capture Mechanism Placeholder**



 Capture bag designed to capture worst case rubble pile, using inflatable exoskeleton forming a cylindrical barrel section and conical section, actual size will depend on target





 Performing various dynamic analyses to assure robust system for capture at slow and fast rotation states while limiting forces on S/C

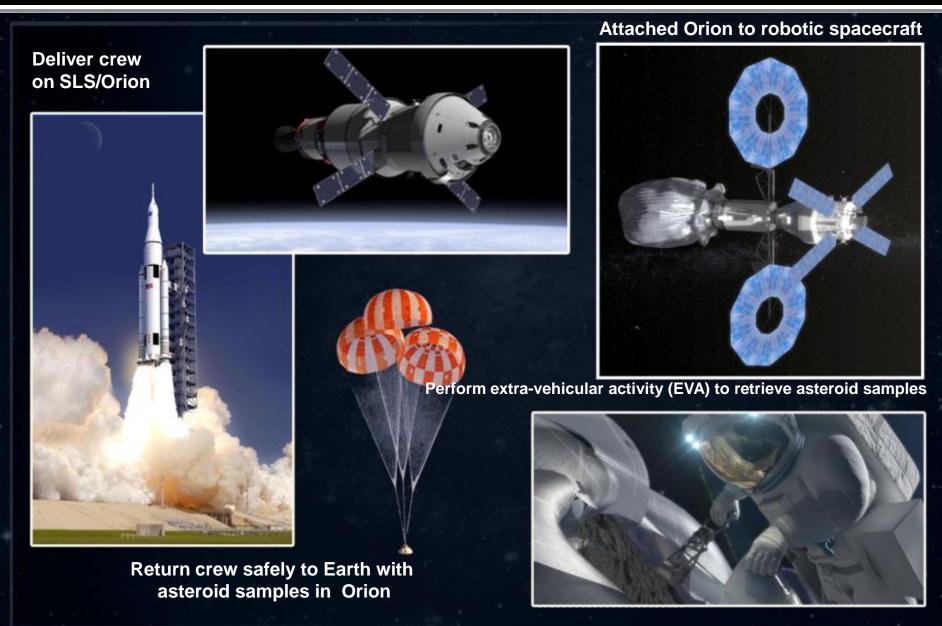


- To help characterize stiffness and damping, forces on the bag, and general control of the bag and fabric
- Upgrades to system to include pie-shaped inner bags for fast rotation capture planned for spring 2014.



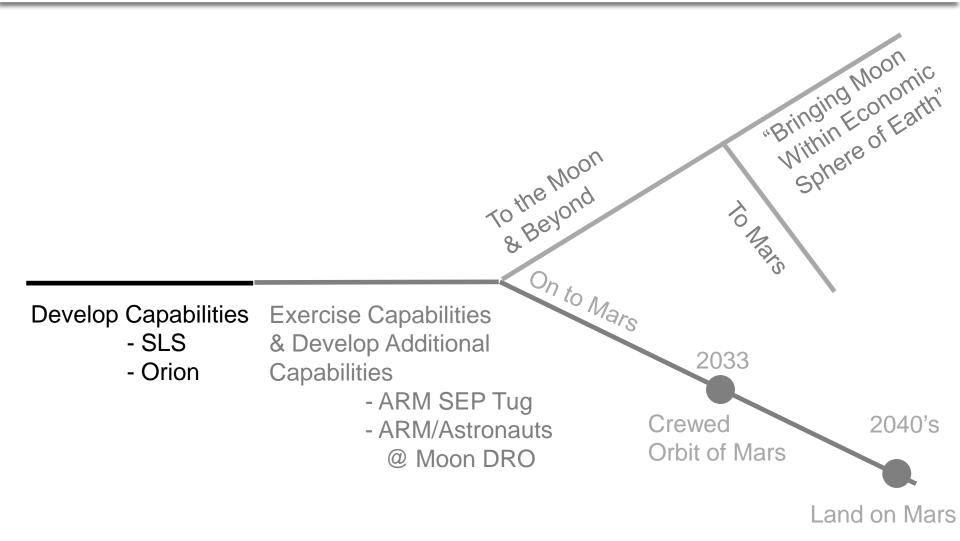
## **Asteroid Redirect Crewed Mission Overview**





## **Example Human Exploration Pathways**





### **FY13 Modified ACES Testing Progress**







MACES EVAs are demonstrated as feasible and neutrally buoyant testing is warranted

June 28th - Test #3 (2hr)



Improvements in suit fit procedures needed

July 22<sup>nd</sup> – Test #5 (2hr)



Great capability improvements observed in subsequent runs indicating that training on the suit is vital.

Sept. 25<sup>th</sup> - Test #8 (4hr)



Best demonstration of suit capabil ity, attributed to good suit fit that allowed the subject easier access to standard work envelope.

May

June

Trub

August

September

May 5<sup>th</sup> – Test #1 (2hr)



Established baseline weigh out and ECS interface (both to be improved)

June 7<sup>th</sup> – Test #2 (2hr)



Established need for robust EVA gloves (EMU PhaseVI)

July 12<sup>th</sup> – Test #4 (2hr)



Two-handed task difficulties established need for suit shoulder biasing and better worksite stabilization

Sept. 6<sup>th</sup> – Test #6 (3hr)



Suit fit specific to EVA operations continues to be a significant performance factor

included

Sept. 16<sup>th</sup> – Test #7 (4hr)



Suit system demonstrated feasibility of 4 hour EVAs.

Hardware and
Procedure
Improvements
Improved weights

Added tool harness
Phase IV Gloves

Cooling System modifications

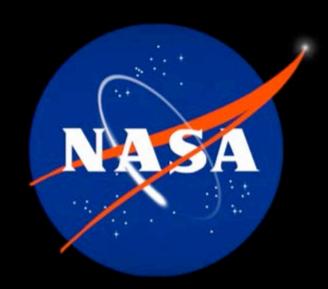
Drink bag

Improved Poolside Procedure

New liquid cooling garment

## **EVA Technique Development**





**Asteroid Mission NBL Testing** 

## **Leveraging Trajectory and Rendezvous**



Outbound

Outbound Flight Time

9 days

Orion DRO

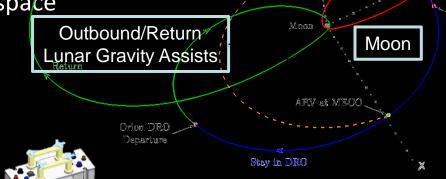
Orion/ARV

Docking

 Common sensors derived from knowledge gained from Space Shuttle Detailed Tests

Synergy between crewed and robotic mission sensors

 Trajectory launch constraints, rendezvous techniques, navigation enable deep space



Return Flight Time 11 days

**EARTH** 





Notional Relative Navigation Sensor Kit

Outbound Flight Time: 8 days, 9 hrs Return Flight Time: 11 days, 6 hrs Rendezvous Time: 1 day

DRO Stay Time: 5 days

## **Docking System**

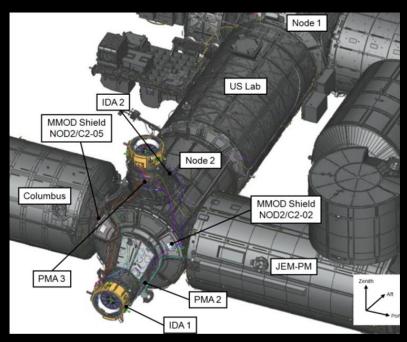


 Docking System for Orion and Robotic Spacecraft leverages development of International Docking System Standard

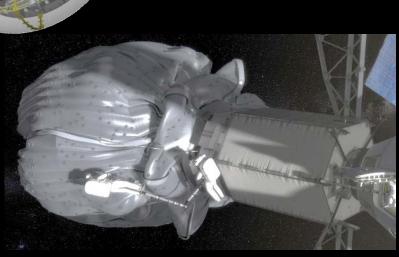
Orion Active
Docking Mechanism
(extended)

Robotic Spacecraft
Passive Docking
Mechanism





- International Docking Adapter will create a docking port on ISS
- Compatible with new International Standard
- Provides Power and data utility connections to visiting vehicles
- Delivered to ISS in trunk of Space –
   X Dragon Cargo Vehicle



## **ARM Provides First Steps to Mars/Other Destinations**



	Mission Sequence	Current ISS Mission	Asteroid Redirect Mission	Long Stay In Deep Space	Mars Orbit	Mars Surface, Short Stay	Mars Surface, Long Stay
Mars Destination Capabilities	In Situ Resource Utilization & Surface Power						Х
	Surface Habitat						X
	Entry Descent Landing, Human Lander					X	X
	Advanced Cryogenic Upper Stage				X	X	X
	Solar Electric Propulsion for Cargo		X	Х	X	X	X
	Exploration EVA		X	Х	X	X	X
on ies	Crew Operations beyond LEO (Orion)		X	Х	X	X	X
Initial Exploration Capabilities	Deep Space Guidance Navigation and Control/Automated Rendezvous		Х	Х	X	Х	Х
	Crew Return from Beyond LEO – High Speed Entry (Orion)		Х	X	X	Х	Х
	Heavy Lift Beyond LEO (SLS)		X	Х	X	Х	X
d	Deep Space Habitat	*		Х	X	Х	X
ISS Derived Capabilities	High Reliability Life Support	*		Х	X	Х	X
	Autonomous Assembly	*		X	X	Х	X

## **Asteroid Initiative Extensibility for future Deep Space/Mars Missions**

#### <u>EVA</u>:

- EVA kits build capability for future exploration:
  - MACES
  - PLSS (Design accommodates Mars)
- Follow-on Asteroid Utilization mission can provide more capable micro-g exploration suit
- Technologies allow NASA to develop the next generation surface suit and PLSS.

Solar Electric Propulsion (SEP)

#### In-space Power and Propulsion:

- High Efficiency Solar Arrays and SEP advance state of art toward capability required for Mars
- Robotic ARM mission 50kW vehicle components prepare for Mars cargo delivery architectures
- Power enhancements feed forward to Deep Space Habitats and Transit Vehicles

High Efficiency Large Solar Arrays

Deep Space Rendezvous Sensors & Docking Capabilities

**Exploration EVA** 

Capabilities

#### **Crew Transportation and Operations:**

- Rendezvous Sensors and Docking Systems provide a multimission capability needed for Deep Space and Mars
- Asteroid Initiative in cis-lunar space is a proving ground for Deep Space operations, trajectory, and navigation.



## **LLCD Mission Architecture**



#### **LLGT UPLINK:**

4 x 10 W 1.55 mm EDFA MOPAS to 10 cm EDFA-pre-amp on LADEE Transmitting 10 or 20 Mbps 4-PPM with ½ Rate code and interleaver

#### **LLGT DOWNLINK:**

0.5 W 1.55 mm EDFA MOPAs to 4 x 0.4 m telescopes to 16 SNDAs Transmitting 40 to 622 Mbps 16-PPM with ½ Rate code and interleaver Lunar Lasercom Space Terminal (LLST)



at NASA's White Sands Complex (WSC)







(LLOT) – "OCTL" at Table Mtn. CA OGS at Tenerife, Spain

LADEE Science Ops Center at GSFC

**RF Ground Station** 

LADEE
Mission Ops Center
at ARC

Lunar Lasercom
Ops Center (LLOC)
& Mission Analysis Center
at MIT/LL

LLCD Monitor at GSFC

## Project Accomplishments — LLST to the Lunar Lasercomm Ground Terminal (LLGT)



#### **Performance to Date:**

- ✓ Regular, instantaneous (seconds!) all-optical acquisition and tracking between LLST and LLGT
- ✓ Error-free D/L to LLGT at 40, 80, 155, 311 Mbps
- √ 622 Mbps D/L regularly achieved with a code word error rate (CER) < 1x10<sup>-5</sup> (Req. < 1x10<sup>-4)</sup>
- ✓ Error-free U/L from LLGT at 10, 20 Mbps
- Initial TOF measurements collected and being processed to allow centimeter-class ranging
- ✓ Error-free operation at low Moon elevation angles (< 4 degrees at White Sands/LLGT!)</li>
- ✓ Operation to within 3 degrees of the Sun at up to 622 Mbps with no degradation at the LLGT!



#### **Operational Achievements to Date:**

- ✓ LLST U/L commanding sent and LLST telemetry received over optical link
- ✓ LADEE spacecraft data downlinked through high-speed data interface to LLST Modem; entire 1 GB LADEE buffer downlinked in < 5 min @ 40 Mbps (LADEE C&DH limit)
- Multiple streaming HD videos transmitted to the Moon and looped back to LLGT at 20 Mbps (limited by U/L rate)
- ✓ All-optical (no RF!) Comm passes using automated scripts to awaken and point LLST on schedule

## **Project Accomplishments – JPL OCTL and ESA OGS Ground Terminals**

**ESA Image of the LLST Beam** 



#### JPL's LLOT Ground Terminal (OCTL)

- Regular, instantaneous (seconds!) all-optical acquisition and tracking between LLST and OCTL
- ✓ Properly-framed, error-free D/L to JPL's OCTL at 40, 80 Mbps
- Operation at low elevation angles of the Moon ( degrees at JPL's Table Mountain/LLOT)
- √ "Hand-off" from WSC to JPL during pass in < 2
  min!
  </p>

#### **ESA's LL-OGS Ground Terminal**

- ✓ Received communication D/L to ESA's OGS at 40 Mbps (new station)
- Fine-tracking on U/L sometimes achieved at LLST, but signal level is still 5 dB too low to permit U/L comm
- Final week of passes will try to exercise improved OGS U/L beam pointing



JPL's OCTL Facility in Southern CA



ESA's LL-OGS on Tenerife, Spain

## **Launch Services Program -- CY13 Launch Highlights**











**January 30, 2013** 



**February 11, 2013** 



June 27, 2013





## **Global Exploration Roadmap**

























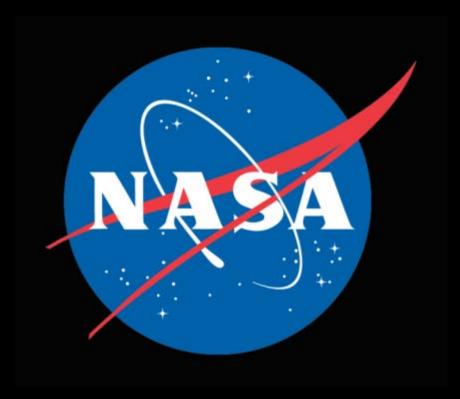




Humans to Lunar Surface

Missions to Deep Space and Mars System

> Sustainable **Human Missions** to Mars Surface



www.nasa.gov